

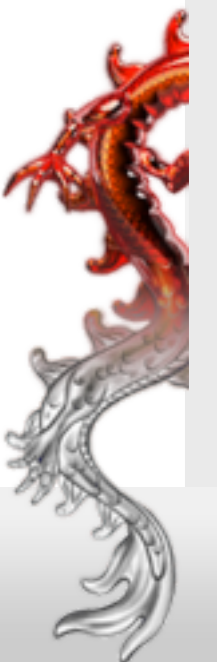
Retargeting From LDR to HDR: Reverse/Inverse Tone Mapping

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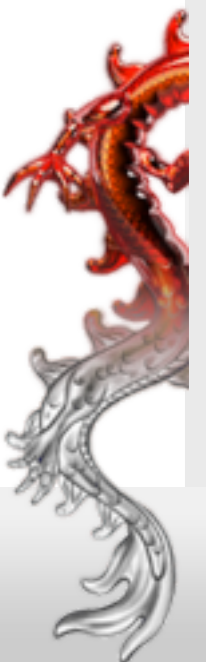
francesco.banterle@isti.cnr.it

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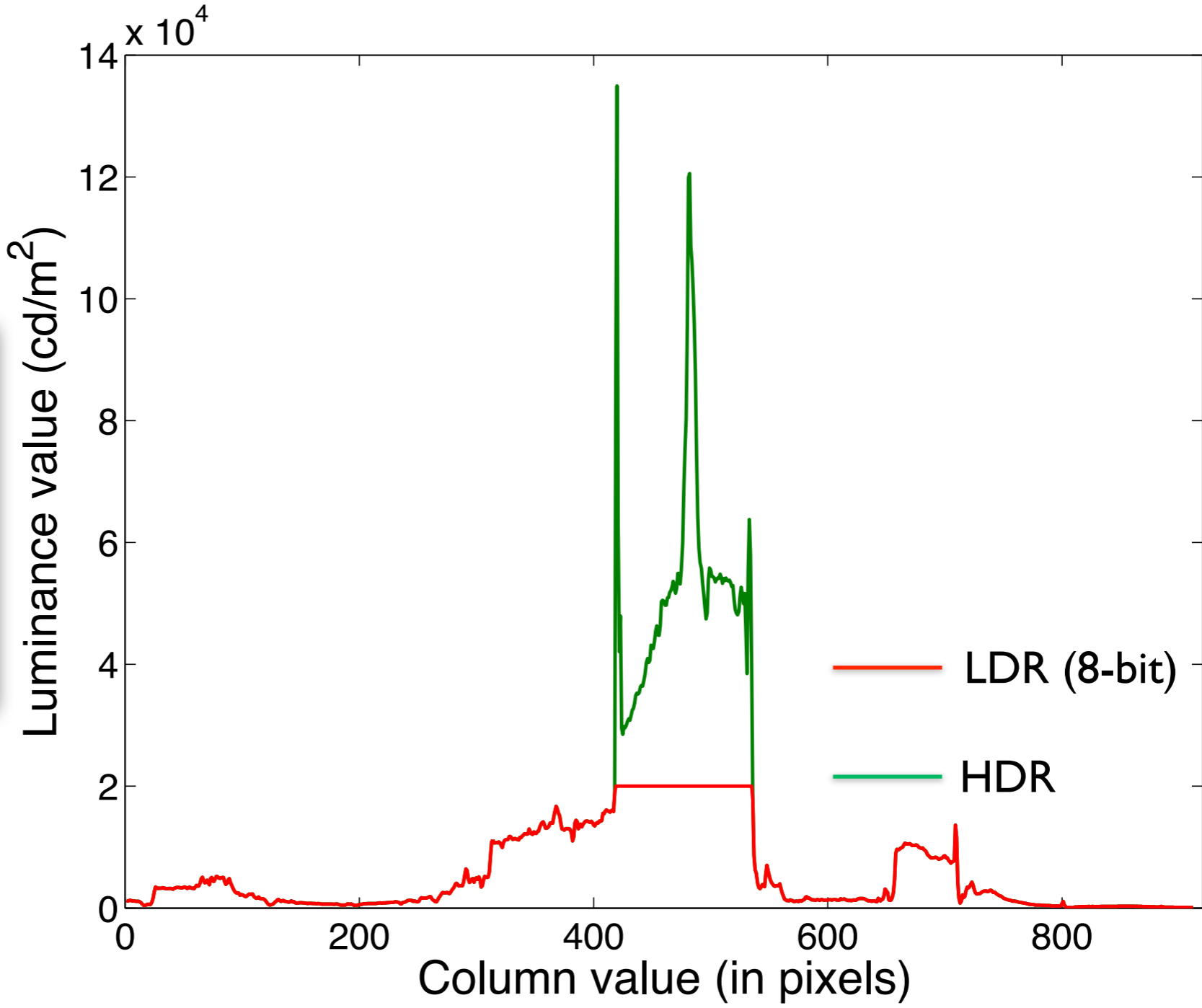


Outline of the Talk

- An Overview on Reverse/Inverse Tone Mapping
- Expansion Methods:
 - Global Methods
 - Expand Map Methods
 - Classification Methods
 - User Based Methods
- Evaluation:
 - Psychophysical Experiments
 - Computational Metrics
- Conclusions



Overview on Reverse/Inverse Tone Mapping



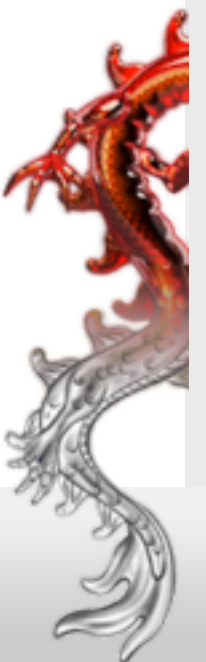
Overview on RTM/ITM: Why?

- Why do we need RTM/ITM?
 - **We want to retarget LDR content into HDR monitors, applications (i.e. Image Based Lighting), and editing!**

- The general operator is typically defined as:

$$g(I) = \mathbb{D}_i^{w \times h \times c} \rightarrow \mathbb{D}_o^{w \times h \times c}$$

- Common steps of these operators:
 - Linearization of the LDR image
 - Noise and quantization reduction
 - Luminance Expansion



Overview on RTM/ITM: Why?

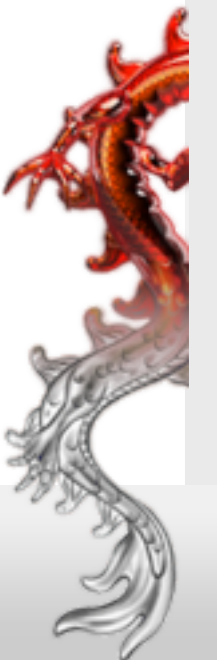
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LDR

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Overview on RTM/ITM: Why?

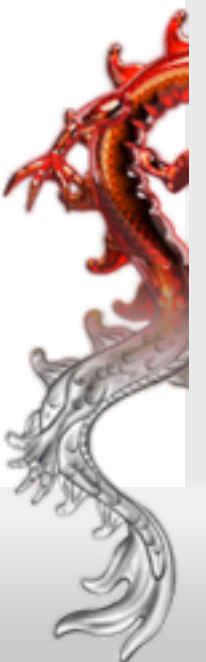
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LDR
HDR

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Global Methods (I)

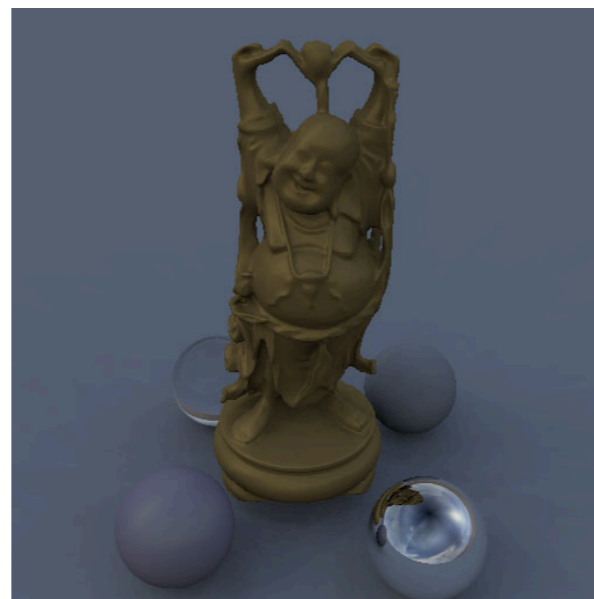
- Landis [Landis02] proposed a simple function for generating HDR images for VFX:

$$L_w(\mathbf{x}) = \begin{cases} (1 - k)L_d(\mathbf{x}) + kL_{w, \max}L_d(\mathbf{x}) & \text{if } L_d(\mathbf{x}) \geq R; \\ L_d(\mathbf{x}) & \text{otherwise,} \end{cases}$$

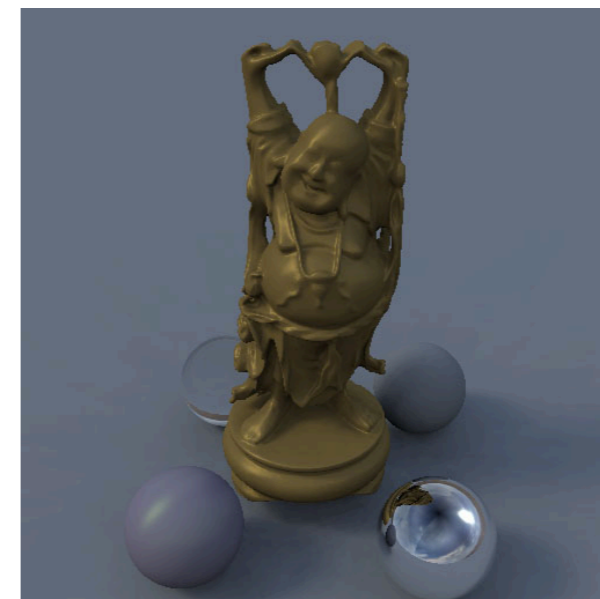
$$k = \left(\frac{L_d(\mathbf{x}) - R}{1 - R} \right)^\alpha,$$



Original LDR EM

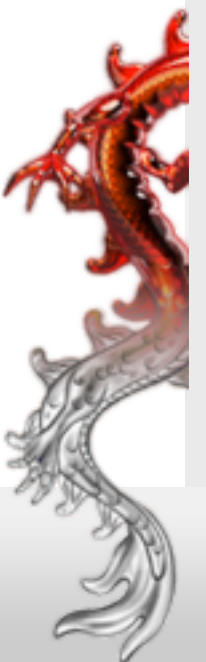


Rendered with LDR EM

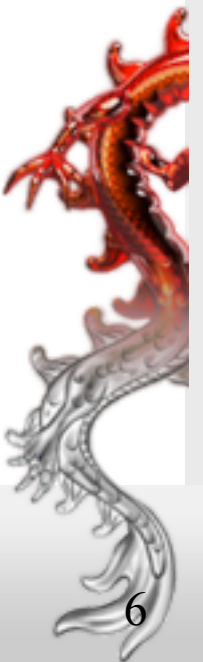
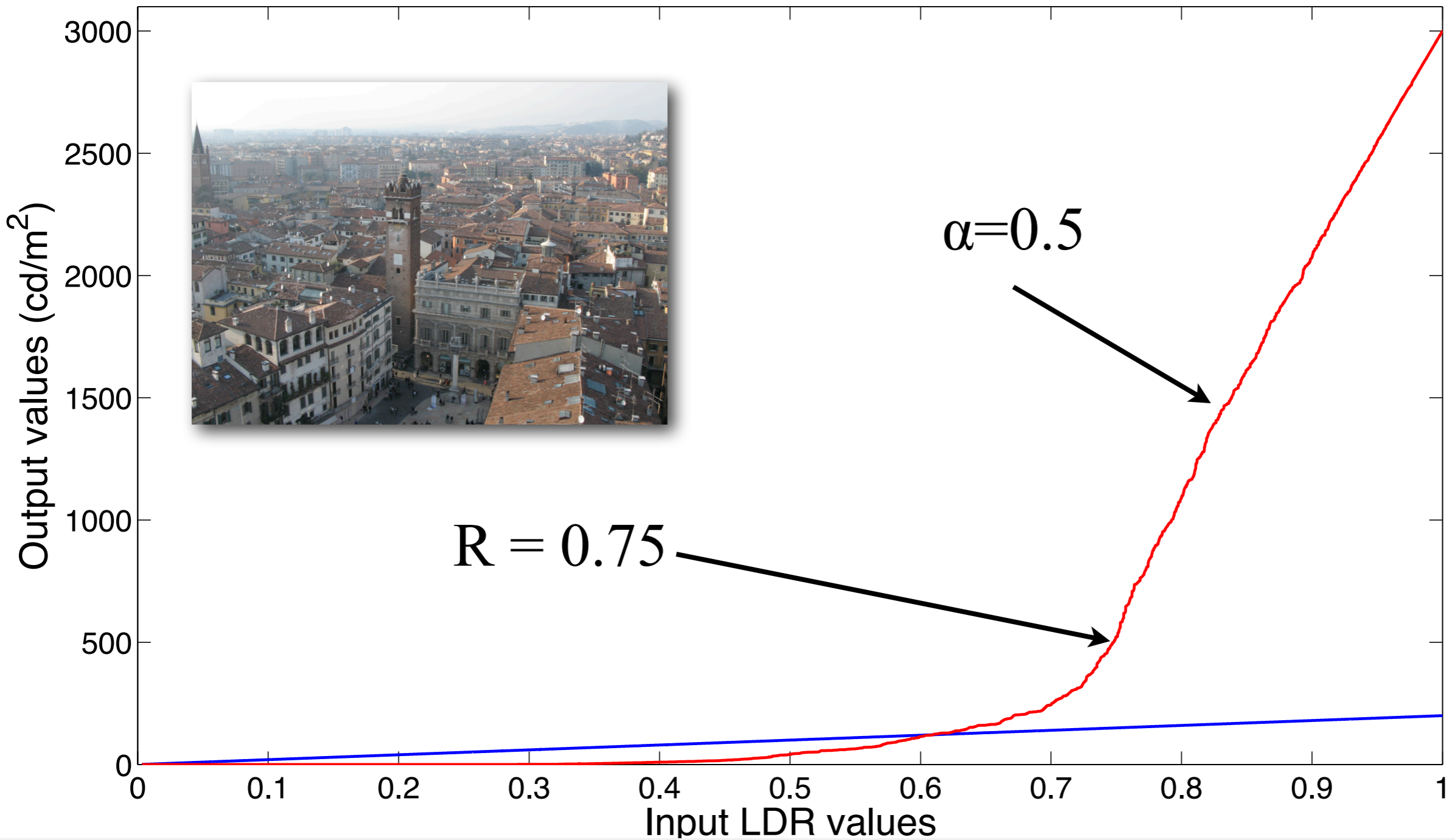


Rendered ITMO EM

LDR Environment map is courtesy of H. Landis [Landis 02]



Global Methods (II)



Global Methods (III)

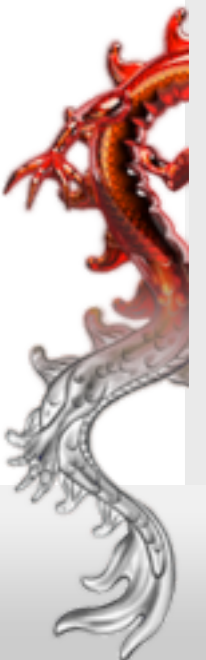
- Akyüz et al. [AFR*07] shown that "**a simple linear scale can provide an HDR experience**" based on psychophysically experiments:

$$L_w(\mathbf{x}) = k \left(\frac{L_d(\mathbf{x}) - L_{d, \min}}{L_{d, \max} - L_{d, \min}} \right)^\gamma$$

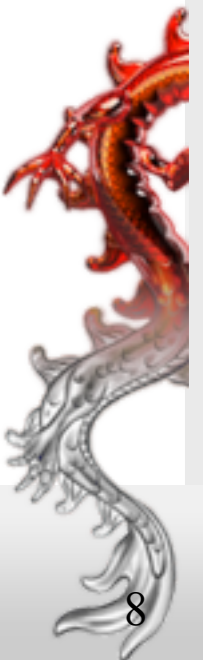
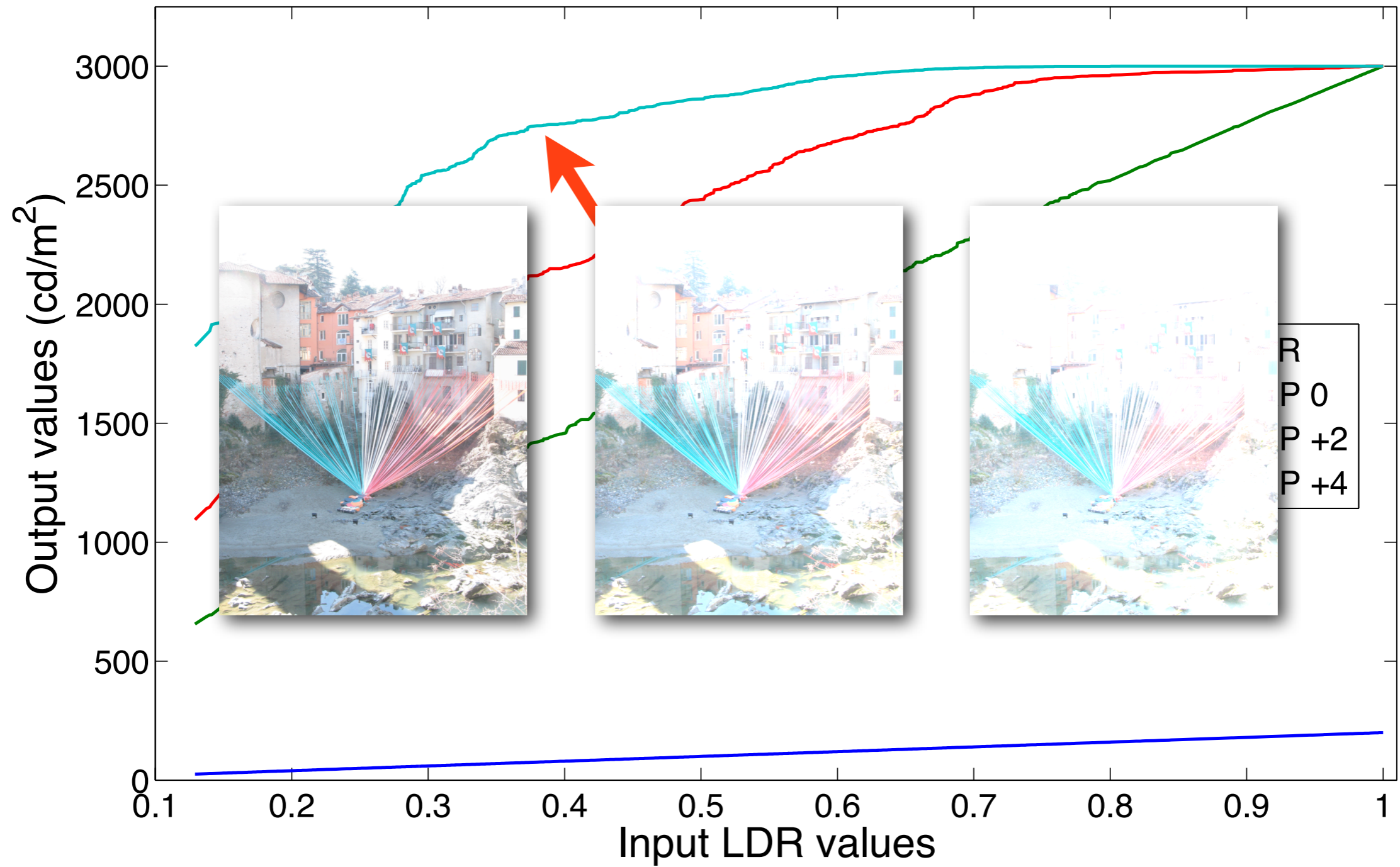
- Masia et al. [MAF*09] shown that for over-exposed images a non-linear function (gamma) needs to be applied. This non-linearity depends on exposedness of the image:

$$L_w(\mathbf{x}) = L_d(\mathbf{x})^\gamma \quad \gamma = 10.44k - 6.282$$

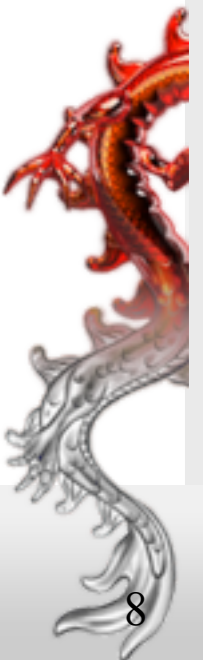
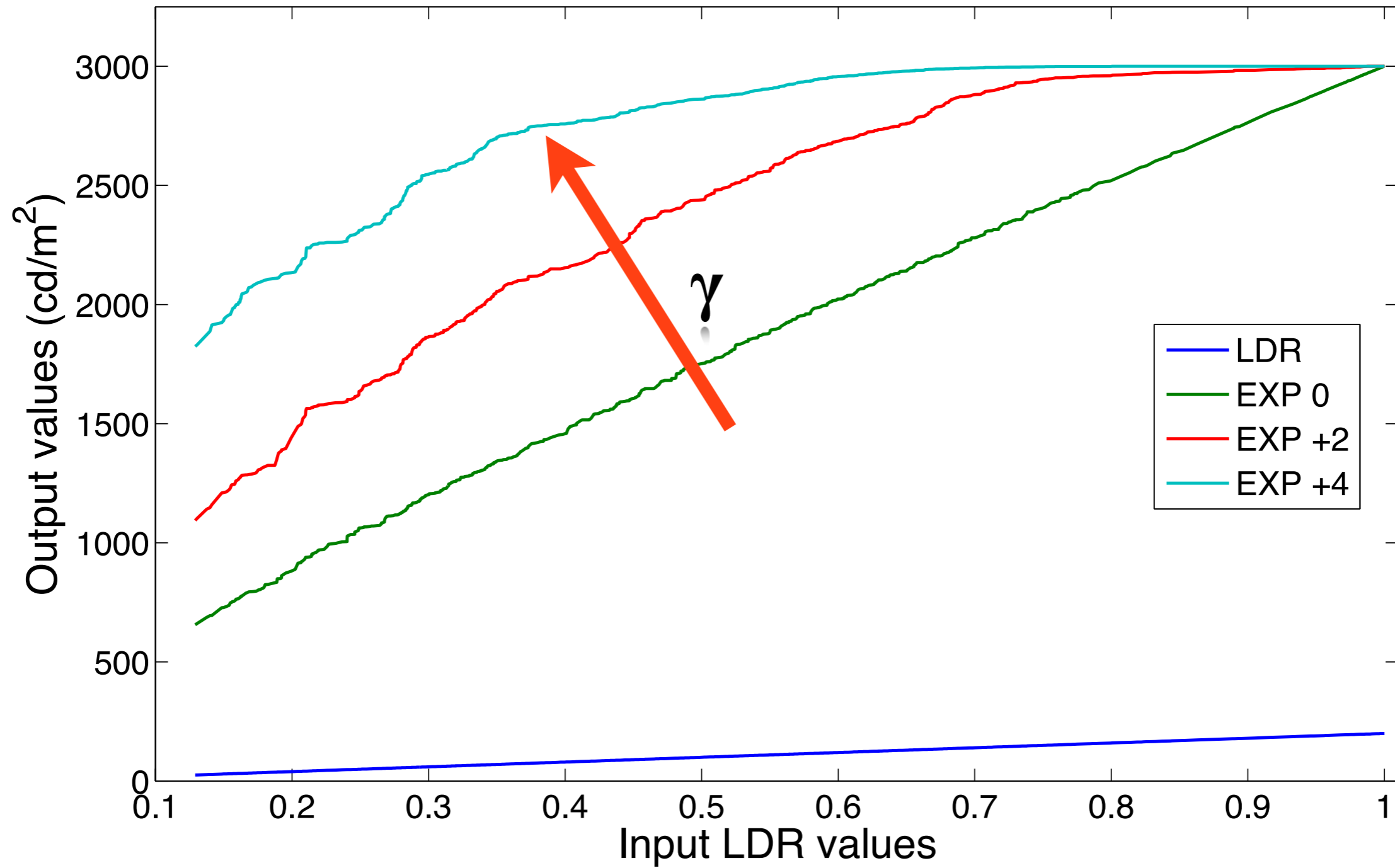
$$k = \frac{\log L_{d, \text{avg}} - \log L_{d, \text{Min}}}{\log L_{d, \text{Max}} - \log L_{d, \text{Min}}} \quad k > 0.65$$



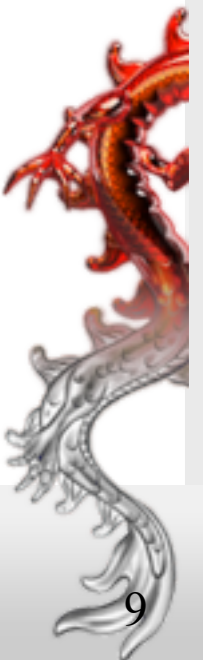
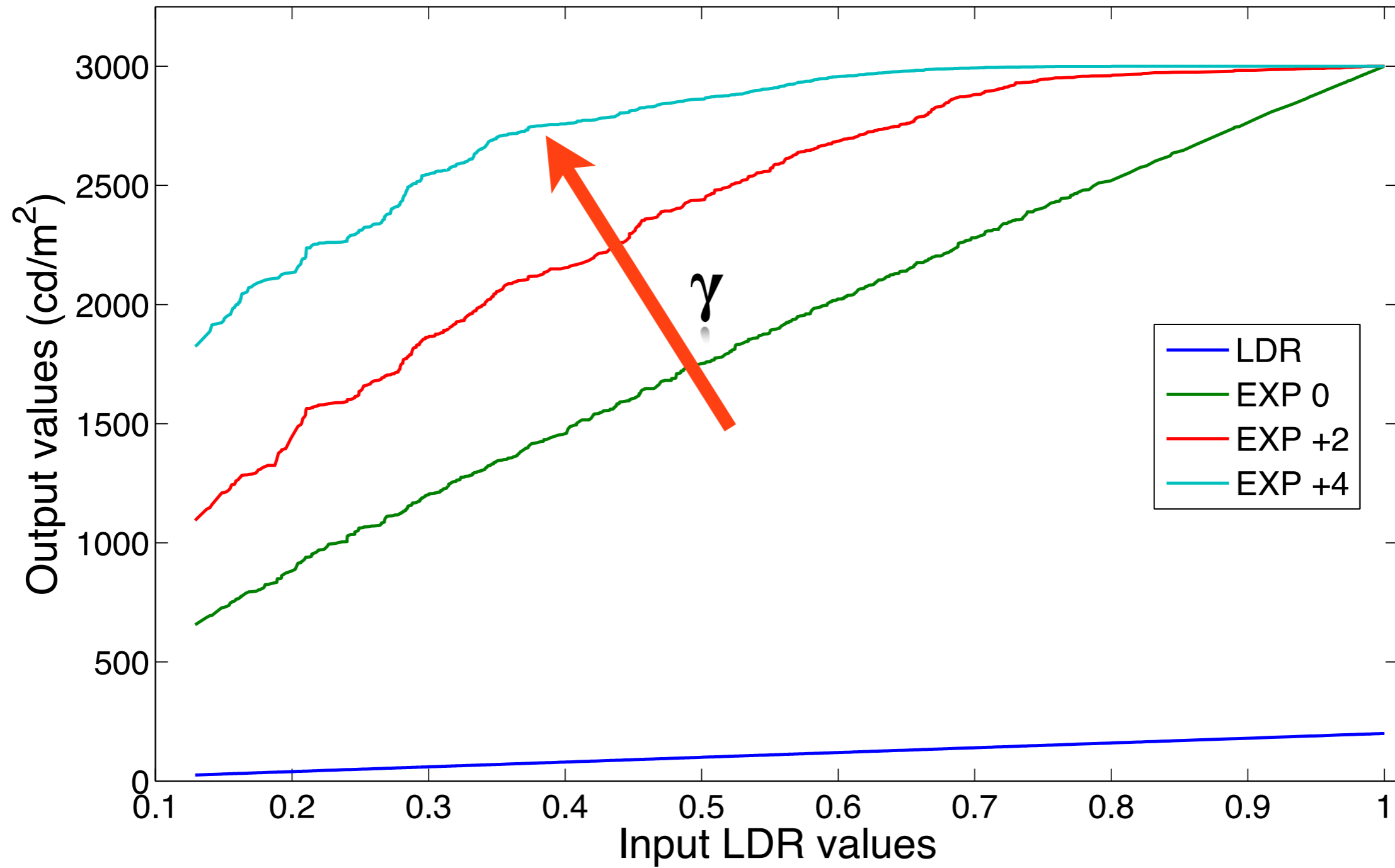
Global Methods (IV)



Global Methods (IV)



Global Methods (IV)



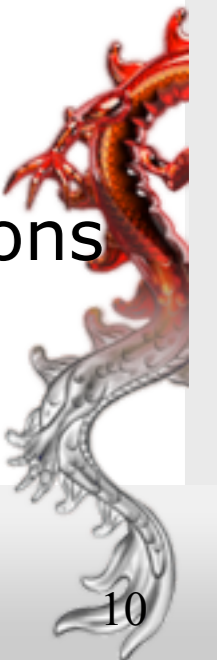
Classification Methods: Highlights Reproduction on HDR Monitors (I)

- Meylan et al. [MDDS06, MDS07] present a classification approach:
 - Expand highlights and specular surfaces ($\omega > 0$)
 - ω is computed using robust thresholding
 - Expansion using a two-scale model:

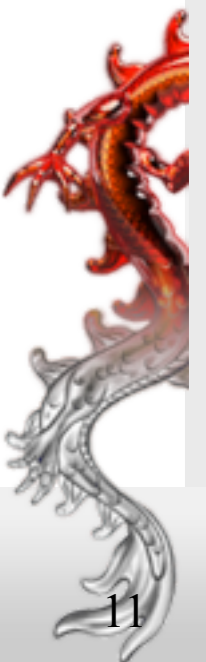
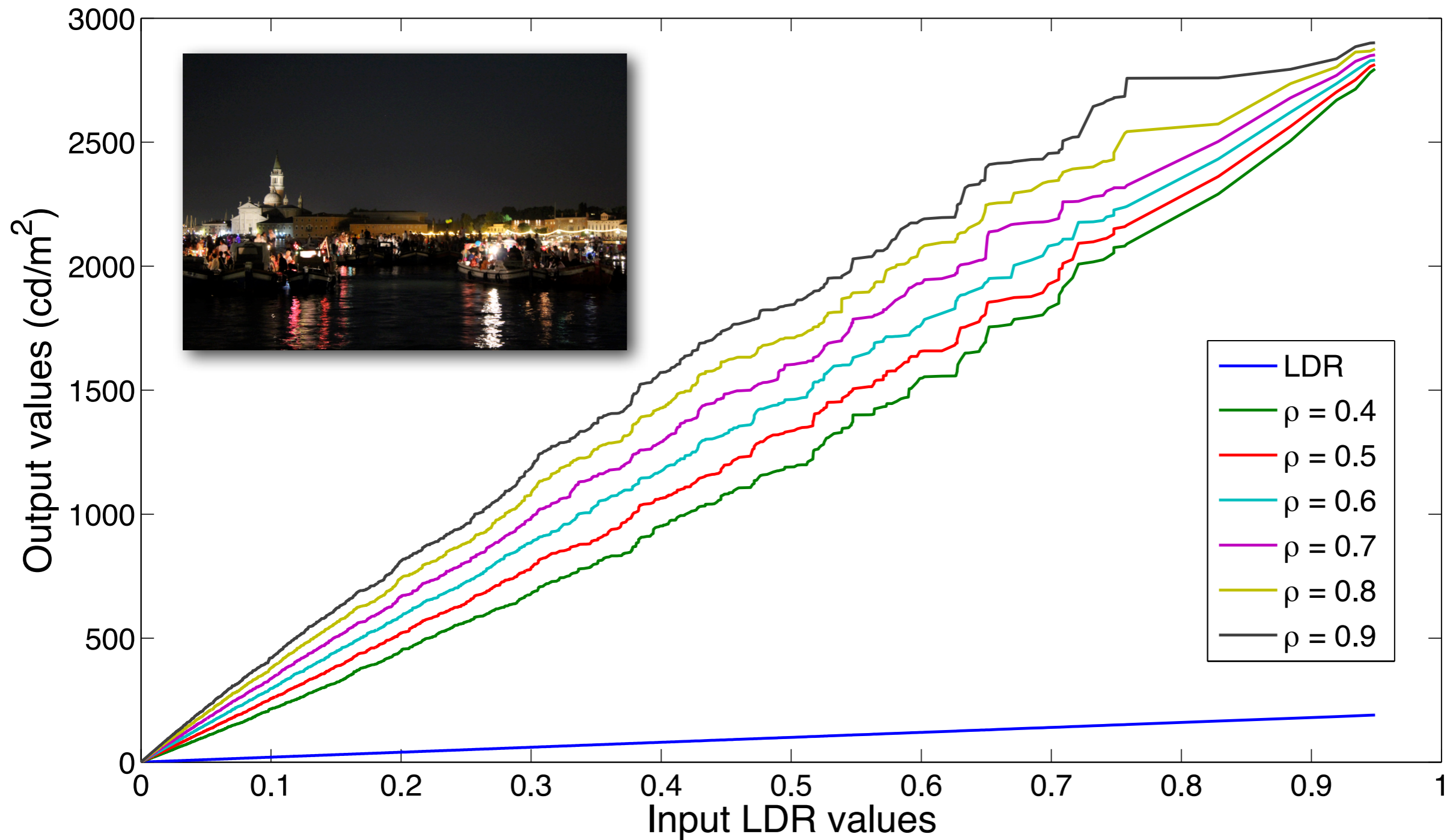
$$L_w(\mathbf{x}) = f(L_d(\mathbf{x})) = \begin{cases} s_1 L_d(\mathbf{x}) & \text{if } L_d(\mathbf{x}) \leq \omega \\ s_1 \omega + s_2 (L_d(\mathbf{x}) - \omega) & \text{otherwise} \end{cases}$$

$$s_1 = \frac{\rho}{\omega} \quad s_2 = \frac{1 - \rho}{L_{d, \text{Max}} - \omega}$$

- To avoid contouring low-pass filtering on expanded regions

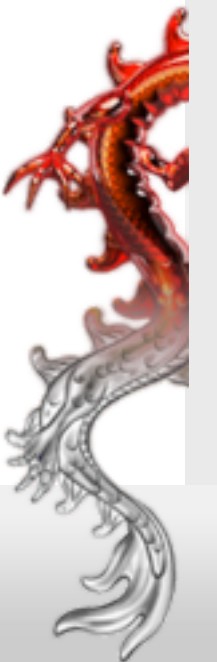


Classification Methods: Highlights Reproduction on HDR Monitors (II)

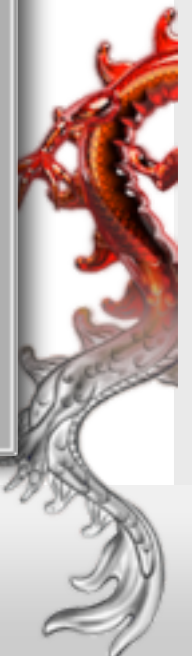
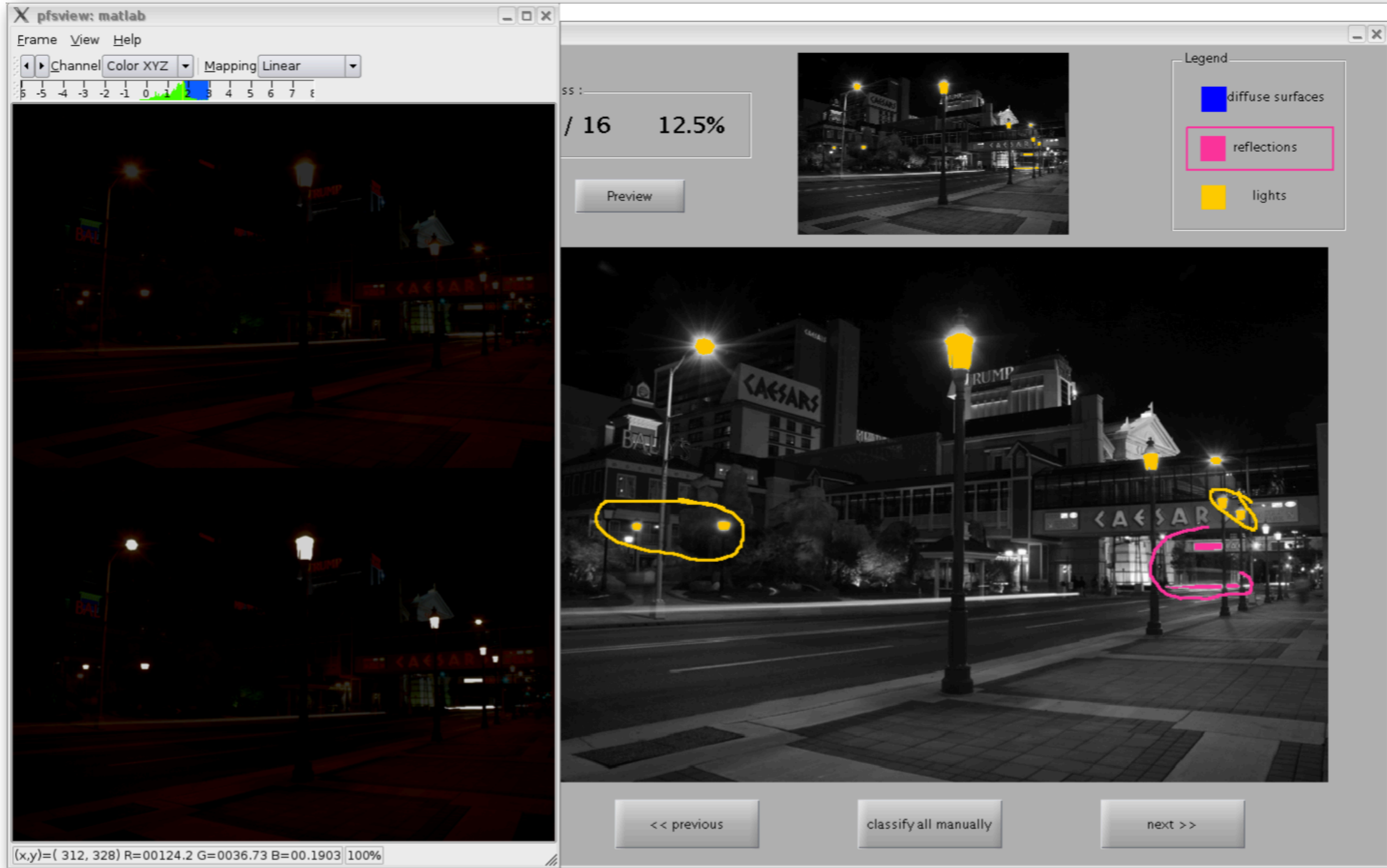


Classification Methods: Enhancement of Bright Videos (I)

- Didyk et al. [DMHS08] extended Meylan et al.'s method:
 - Three classification areas: diffuse, reflections, and lights
 - Automatic Classifier (AC):
 - SVM + Nearest Neighbor + Tracking \Rightarrow 3% error
 - User interface for adjusting the AC errors
 - Non-linear adaptive tone curve for expanding the range based on the histogram of the region:
 - Bilateral filtering layers separation (high and low frequencies) for avoiding contouring



Classification Methods: Enhancement of Bright Videos (II)

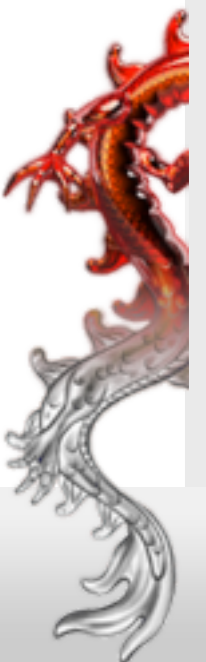


Classification Methods: Selective Reverse Tone Mapping (I)

- Masia et al. [MFSG10] proposed a novel approach based on saliency:
 - **Range Expansion (RE)**: piece-wise linear expansion using the zonal system by Adams (9 zones):

$$p = \left(\frac{\exp(v \sin(\pi \frac{z-1}{16})) - 1}{\exp(v) - 1} \right)^{\frac{1.0}{2.2}} \quad v = 5.25 \quad z \in [0, 9]$$

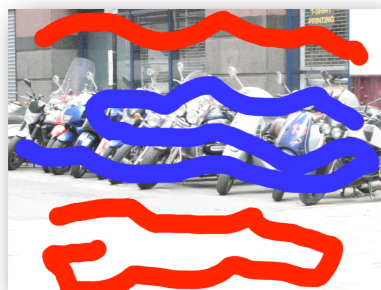
- **Labeling:**
 - salient objects and background discrimination using different techniques:
 - learning-based saliency detection (Liu et al. [LSZ*07])
 - *saliency cuts* (Fu et al. [FCLL08])
 - Different Labels \Rightarrow Different RE functions



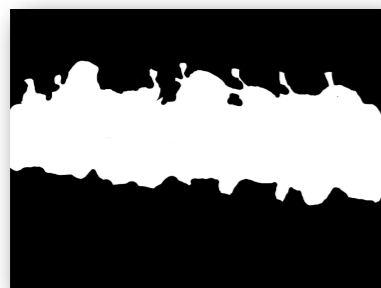
Classification Methods: Selective Reverse Tone Mapping (II)



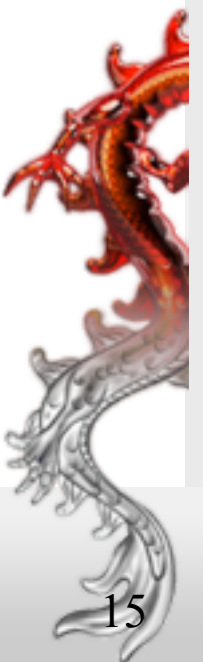
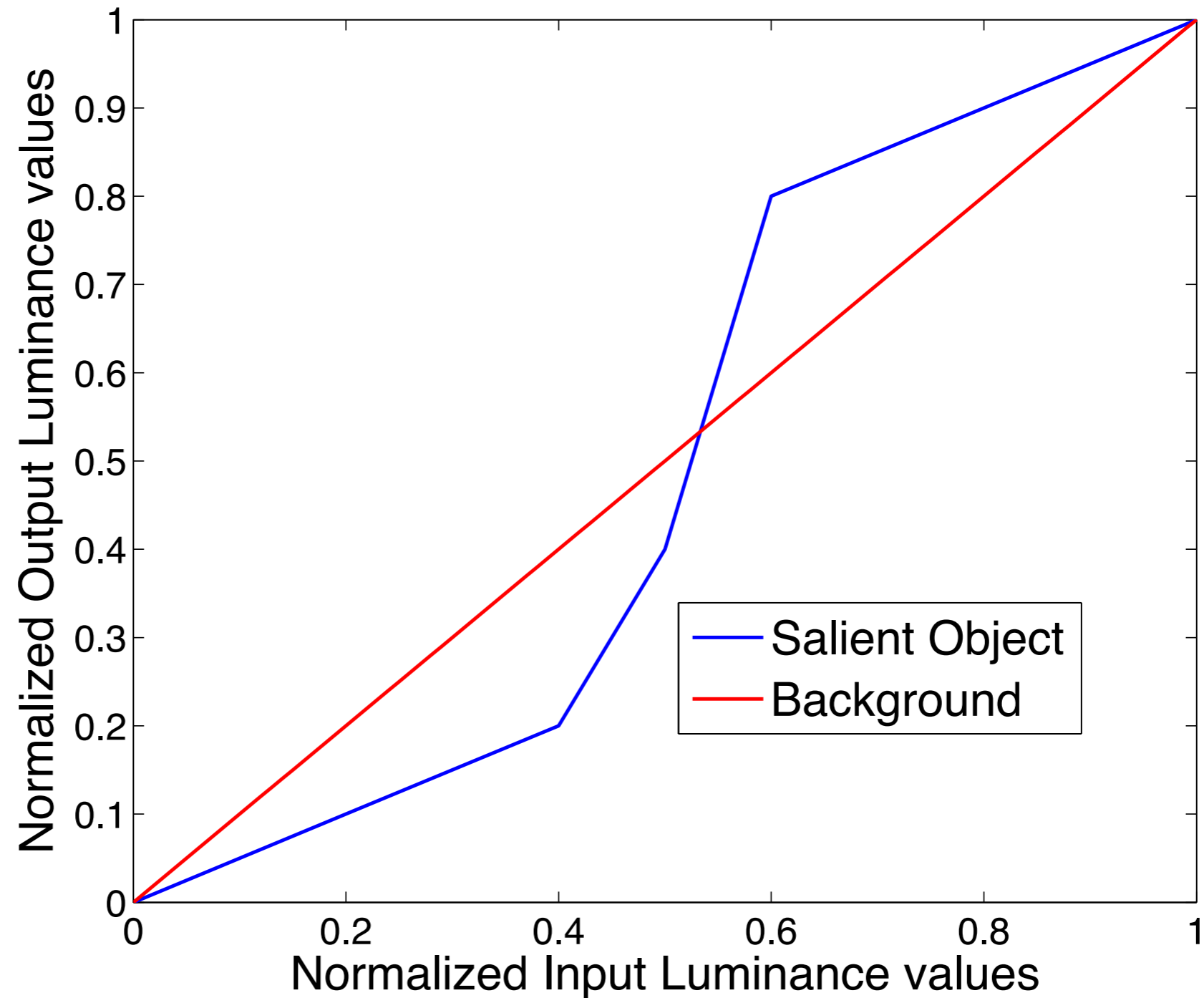
Input



Auto-Labeling

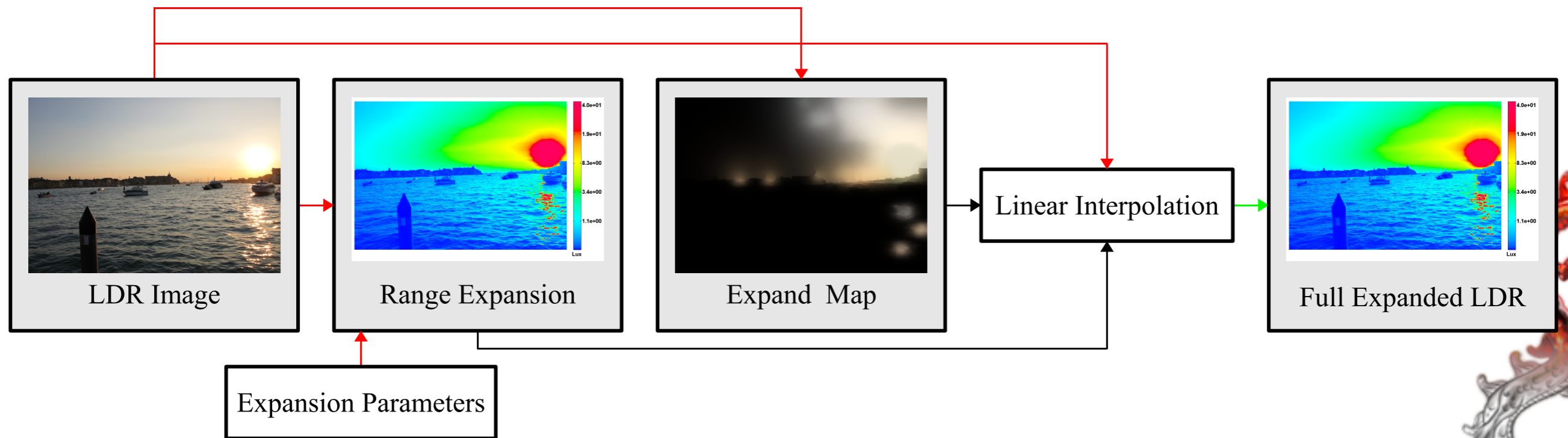


Binary Mask

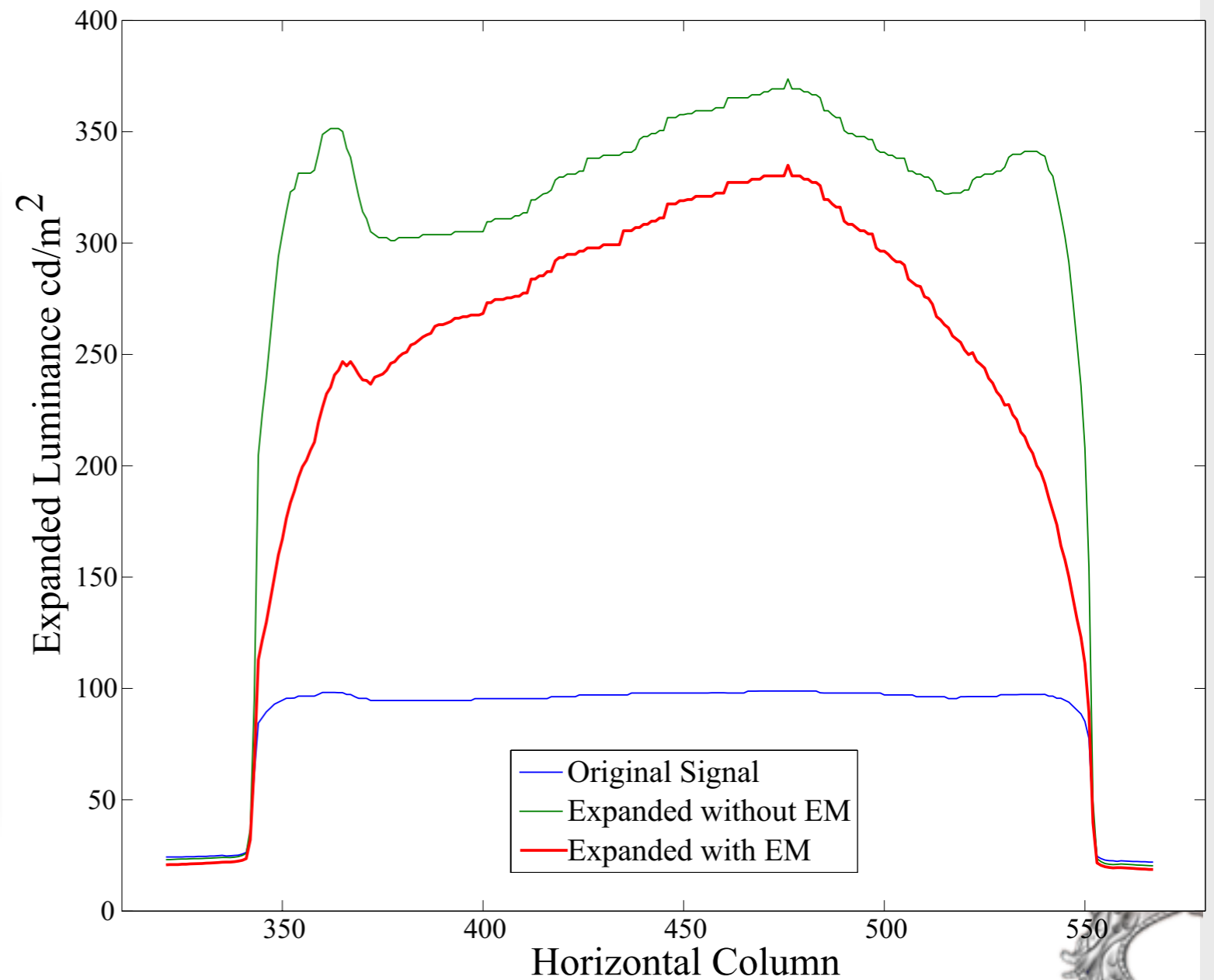
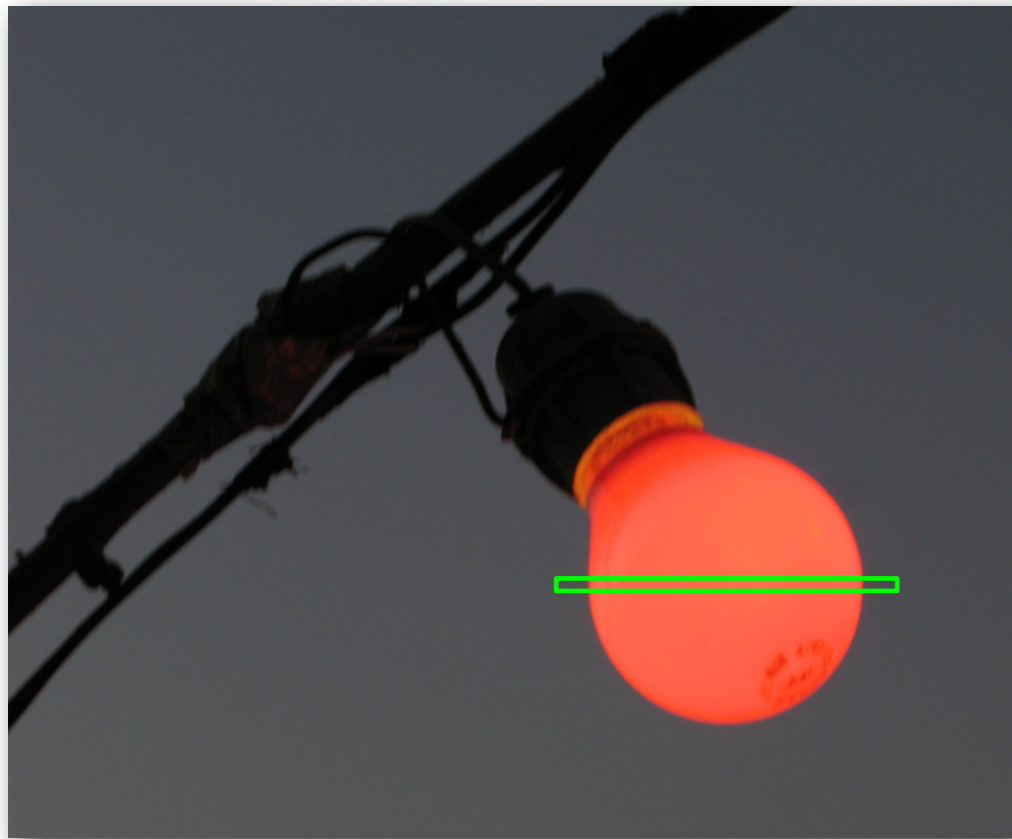


Expand Maps Methods: Non-Linear Expansion using Expand Maps (I)

- Banterle et al. [BLDC06,BLDBC07,BLDC08,B09] presented a general and real-time framework:
 - **Range Expansion:** non-linear (inverting an TMO; other functions)
 - **Expand Map:** sampling+density estimation+cross bilateral (avoiding contouring and compression artifacts)



Expand Maps Methods: Non-Linear Expansion using Expand Maps (II)



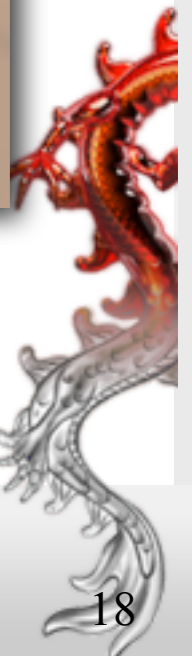
Expand Maps Methods: Non-Linear Expansion using Expand Maps (II)



IBL using original HDR

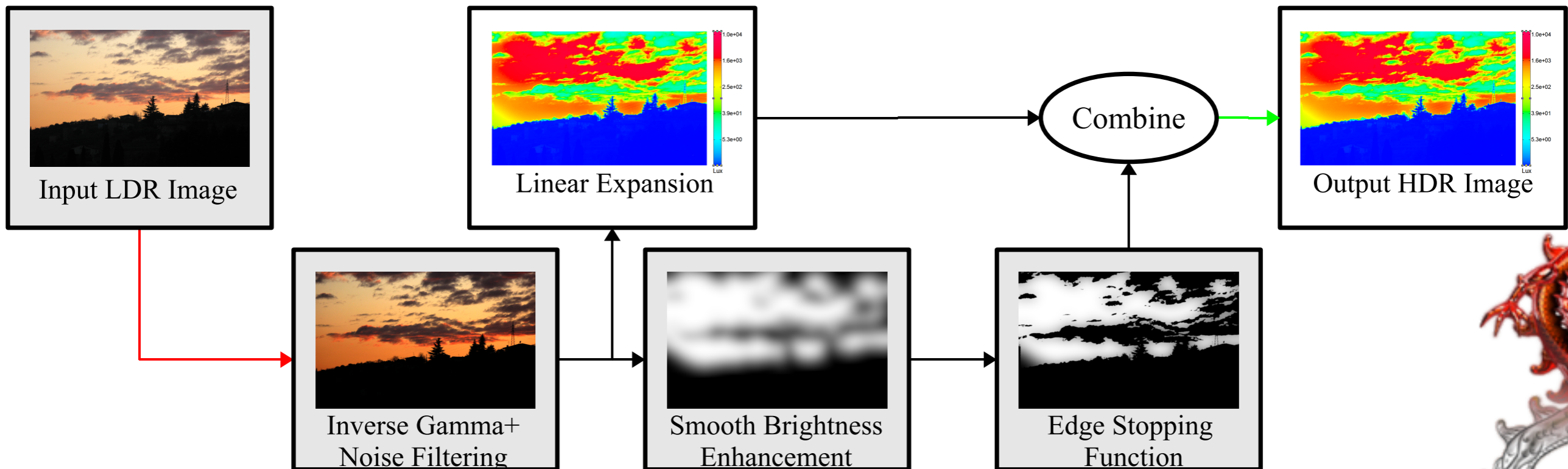


IBL using expanded LDR



Expand Maps Methods: LDR2HDR (I)

- Rempel et al. [RTS*07] presented a similar work of Banterle et al.:
 - **Range Expansion:** linear
 - **Expand Map:** thresholding+filtering+edge stopping



Expand Maps Methods: LDR2HDR (II)



- A variant of the algorithm was presented by Kovaleski and Oliveria [KO09] using the bilateral grid to improve the quality of the Expand Map.

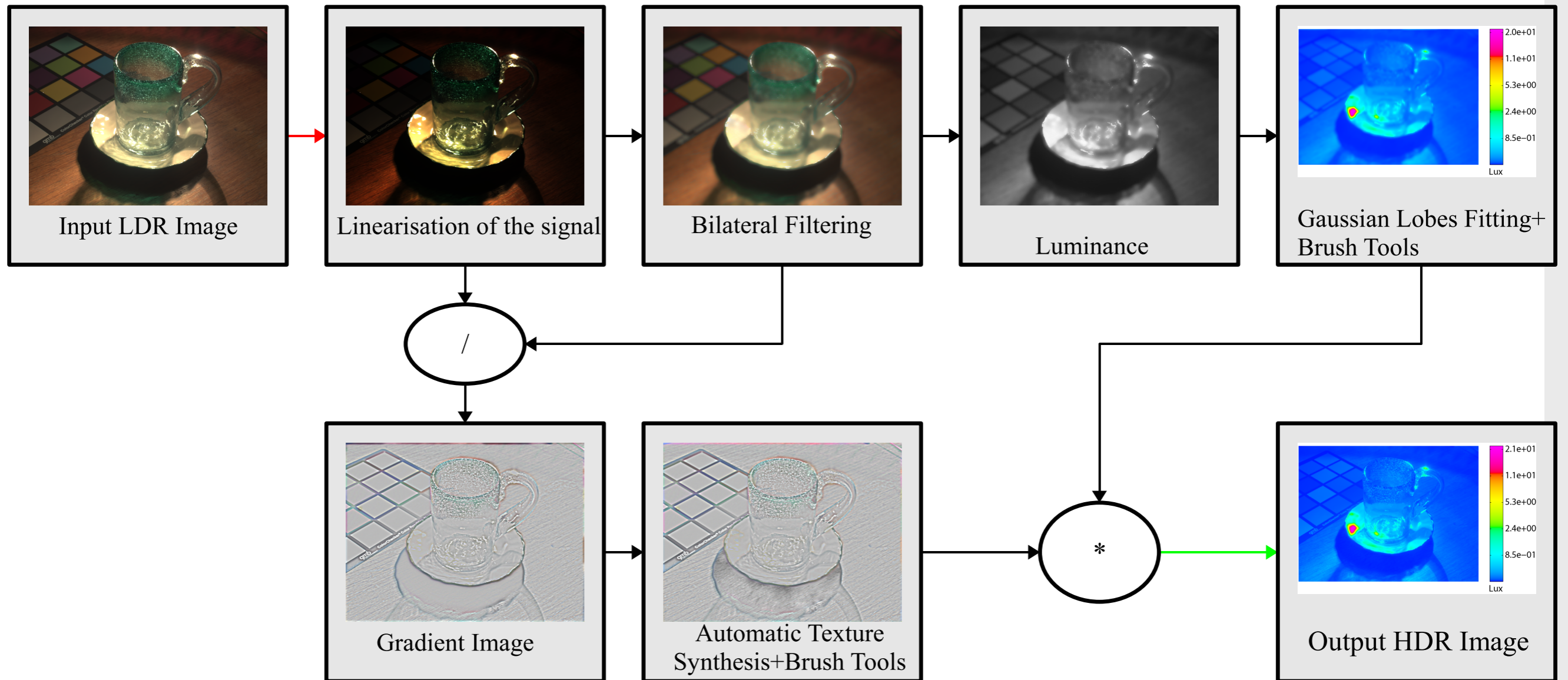


User Based Methods: Hallucination (I)

- Wang et al. [WWZ*07] proposed the first user based method with reconstruction of details:
 - **HDR frequencies using the bilateral filter:** base (low) and detail (high) layers
 - **Automatic Expansion (base layer):** saturated regions are fitted using 2D Gaussian lobes (elliptical)
 - **Reconstruction (detail layer):**
 - Automatic: texture synthesis
 - User-based: Stamp tool (similar to the Healing tool of Photoshop 7)
 - NOTE: other images can be used as source for the missing details

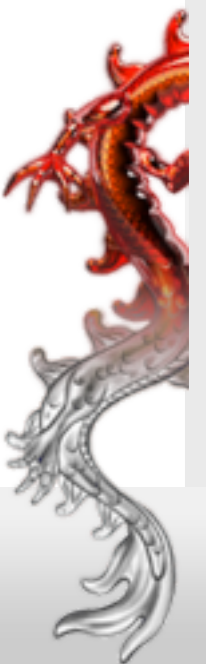
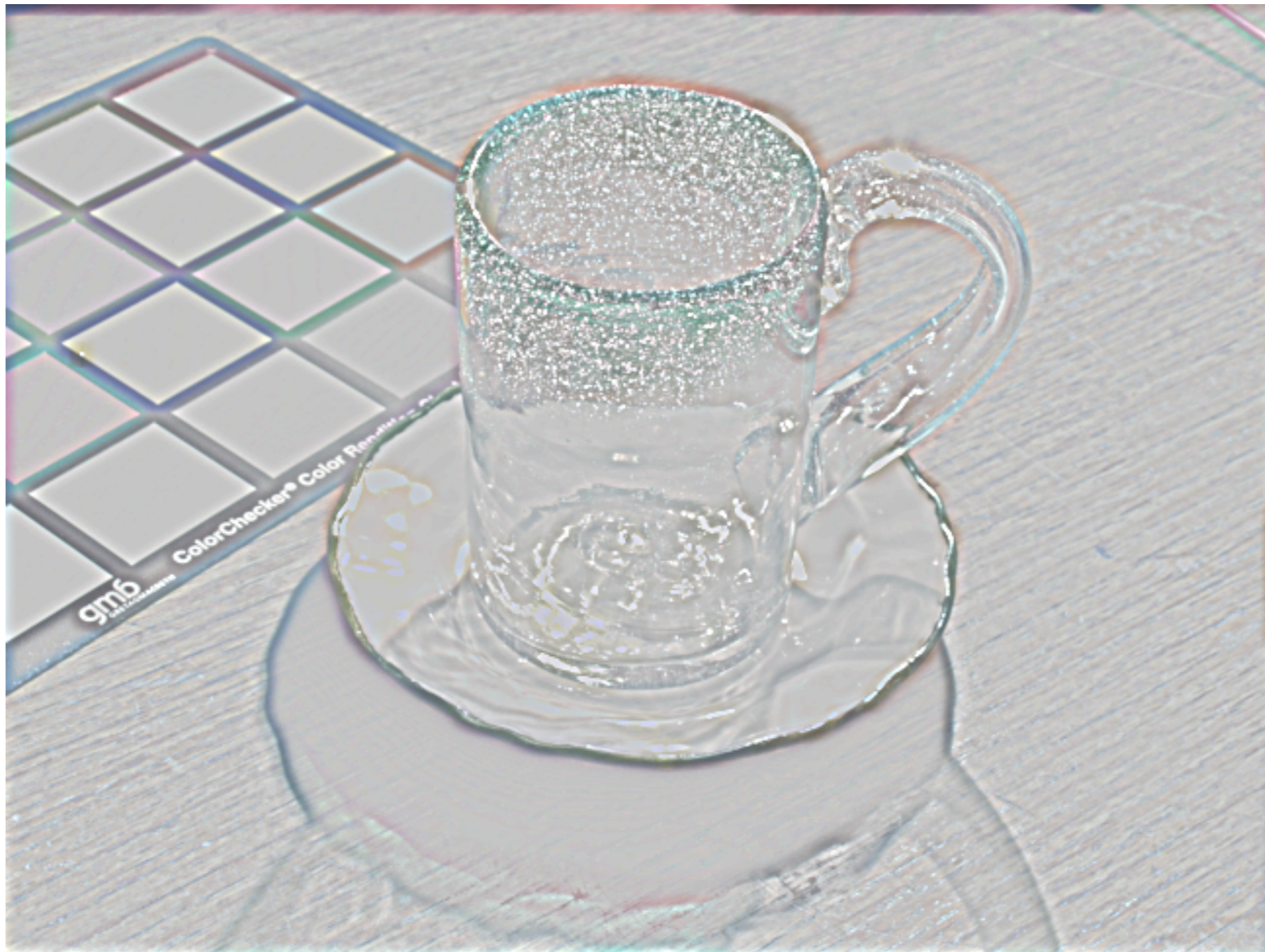


User Based Methods: Hallucination (II)

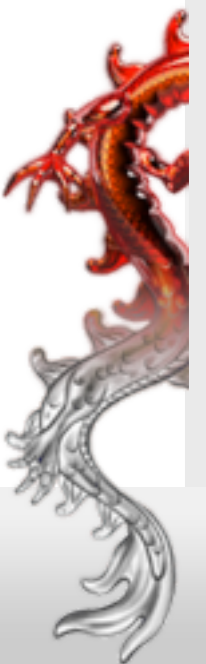
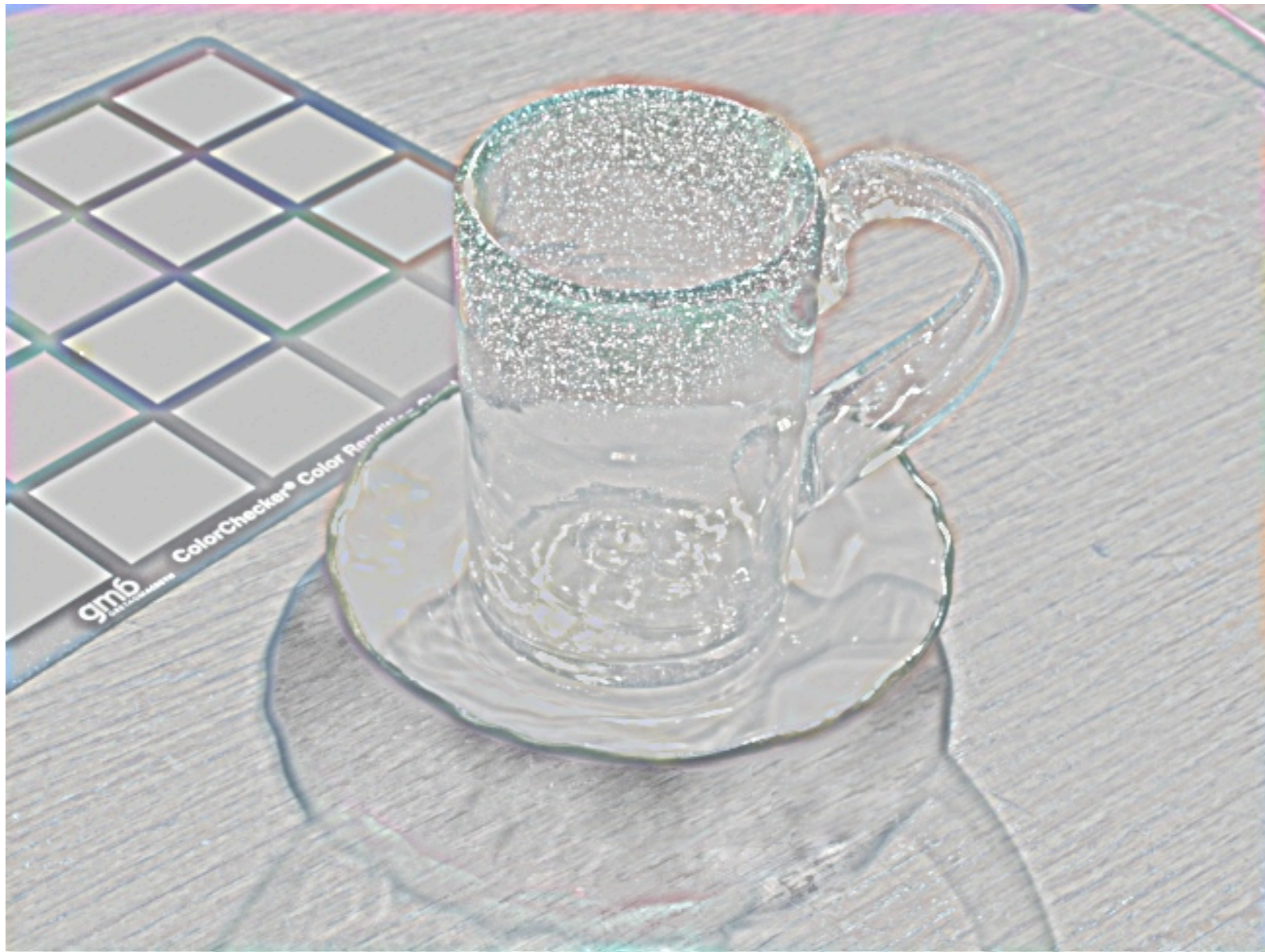


Mexican Mug's image is courtesy of Ahmet Oguz Akyuz

User Based Methods: Hallucination (III), Copying Fine Details in the Detail Layer

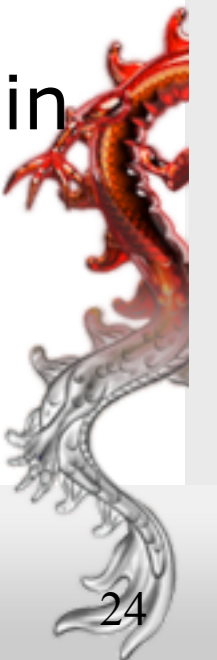


User Based Methods: Hallucination (III), Copying Fine Details in the Detail Layer



Evaluation: Why validation

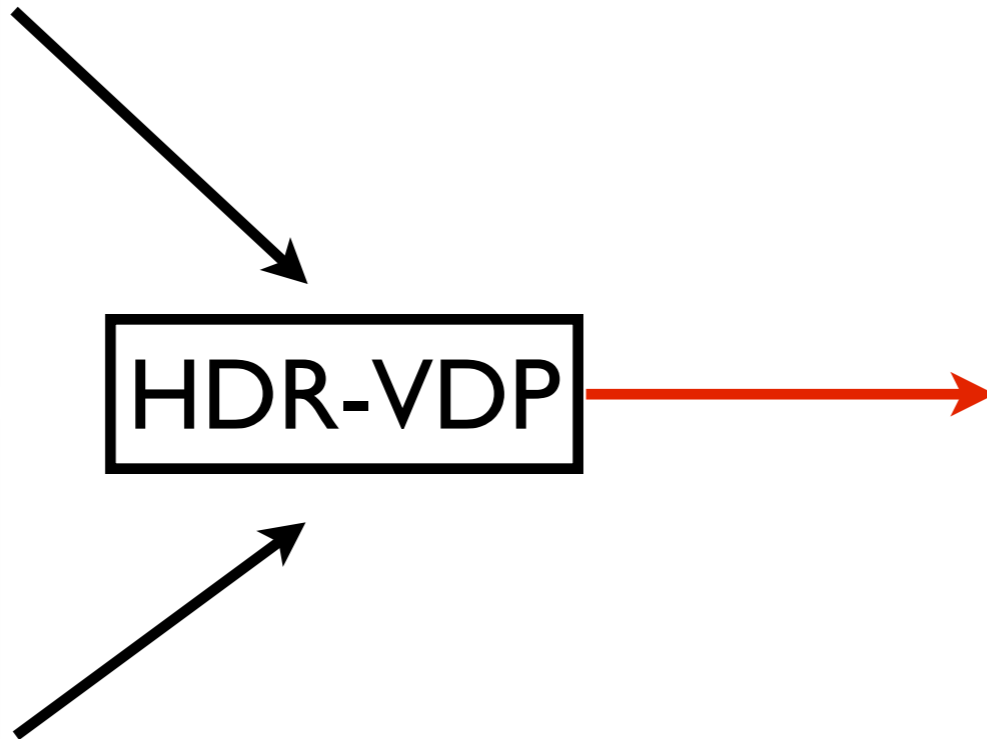
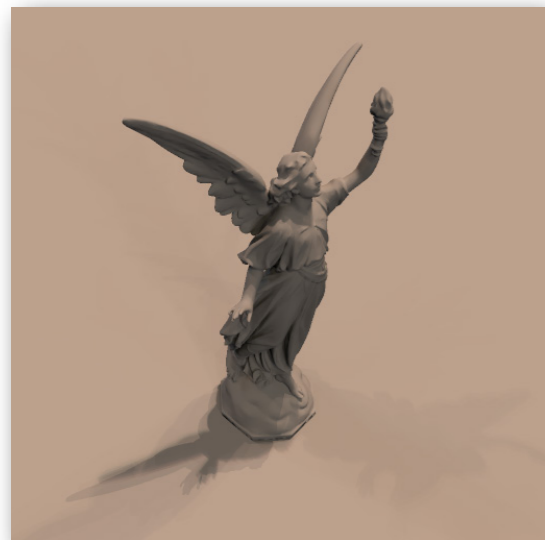
- Need to evaluate different expansion methods against a “*ground truth*”. Why?
 - To understand weak features or drawbacks
 - To understand important features
- rTMO/iTMO techniques do not generate exact luminance values
- Evaluation:
 - Perceptual Image Metrics: not exact comparison as in the PSNR, RMSE, etc.
 - Psychophysical Experiments



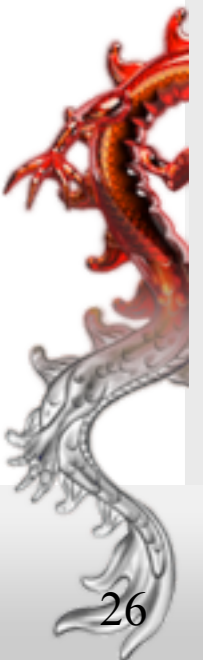
Evaluation: Perceptual Image Metrics

- **HDR-VDP** (current version 2.1) [MDMS04,MKRH11]: determines the probability for each pixel of being different:
 - Banterle et al. [BLDC06,BLDCB07,BLDC08,B09] used it to validate that their models were performing better than a simple non-linear expansion, validate against other methods, etc.
- **DI-IQA** [AMMS08]: detects changes in details visibility, quantization artifacts. Validation of the quality in general:
 - Masia et al. [MAF*09] and Kovaleski and Oliveria [KO09] used it to prove that their methods introduce less distortions during LDR expansion

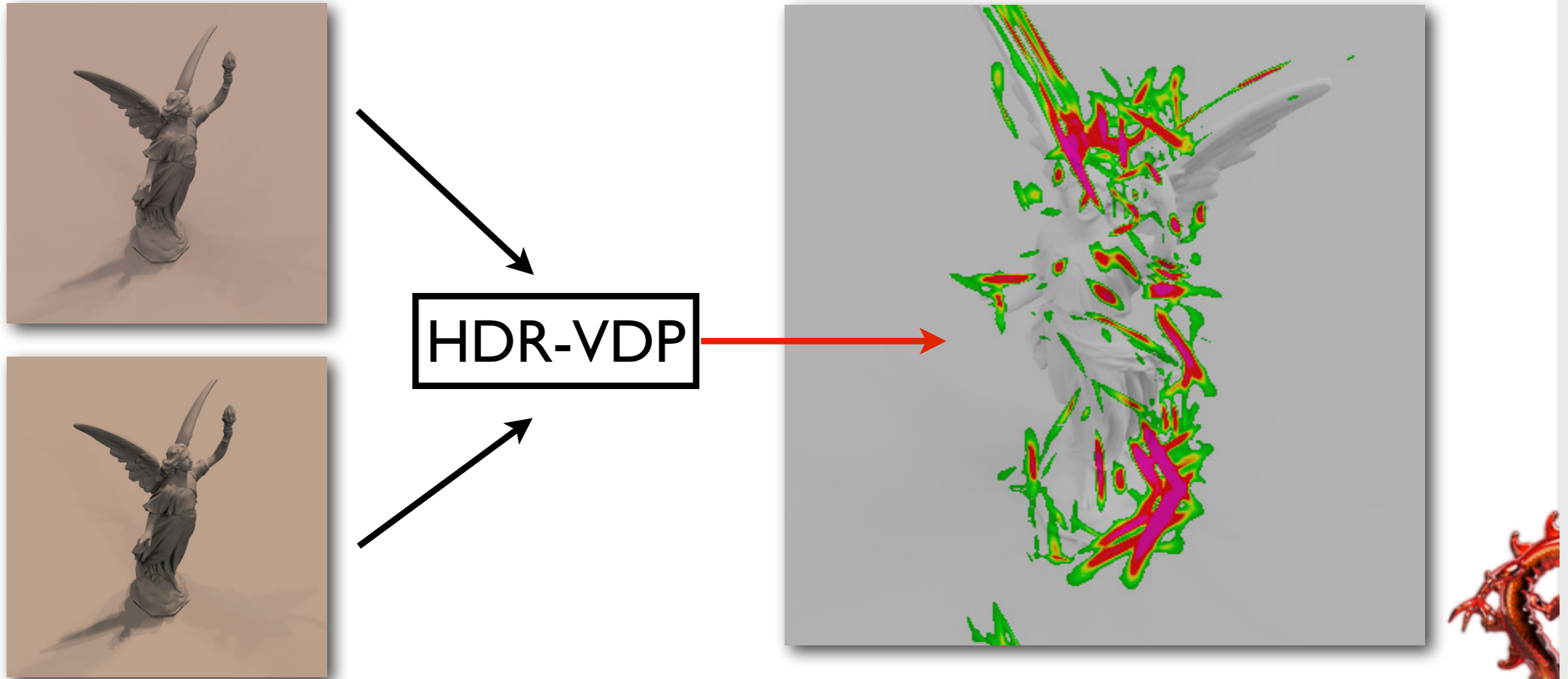
Evaluation: Perceptual Image Metrics (II)



Lucy model is courtesy of the Stanford 3D Scanning Repository



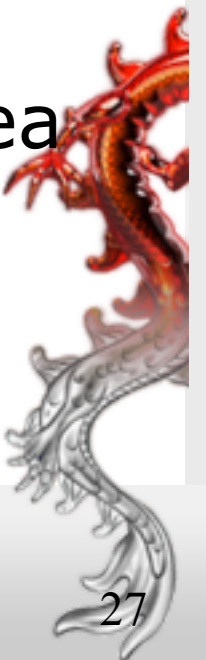
Evaluation: Perceptual Image Metrics (II)



Lucy model is courtesy of the Stanford 3D Scanning Repository

Evaluation: Psychophysical Experiments

- Pairwise comparisons of HDR videos [DMHS08]:
 - validation of the method against LDR, and LDR2HDR
- Pairwise comparisons of HDR images [BLD*09]: comparisons for image visualization and IBL:
 - quantization artifacts need to be handle for better quality.
 - IBL needs non-linear expansion.
- Rating of HDR images and tone mapped expanded images [MAF*09]:
 - understanding preferences in very over-exposed area
 - understanding artifacts in expanded images.



Conclusions:

- LDR Expansion for HDR applications:
 - LDR expansion methods are needed to be used in HDR applications (HDR visualization, Image Based Lighting, etc.)
 - The size of over/under-exposed areas is a limitation when recreating the content
- What's important?
 - To have non-linearity or controllable expansion functions
 - Avoid artifacts' boosting: quantization and JPEG-like compression
 - Take care of over-exposed areas differently

